

Lecture 15 - 04-05-2020

1.1 Regret analysis of OGD

We introduce the **Regret**.

$$\frac{1}{m} \sum_{t=1}^T \ell_t(w_t) - \frac{1}{T} \sum_{t=1}^T \ell_t(u_t^*)$$
$$(x_1, y_1) \dots (x_t, y_t) \quad \ell_t(w) = (w^T x_t - y_t)^2$$

we build a loss function for example with the square loss.

The important thing is that ℓ_1, ℓ_2, \dots is a sequence of **convex losses**.

In general we define the regret in this way:

$$R_T(u) = \sum_{t=1}^T \ell_t(w_t) - \sum_{t=1}^T \ell_t(u_t)$$

The Gradient descent is one of the simplest algorithm for minimising a convex function. We recall the iteration did by the algorithm:

$$w_{t+1} \leftarrow w_t - \eta_t \nabla f(w_t) \quad \eta_t > 0 \text{ **learning rate** } \quad f \text{ convex}$$

$f : \mathbb{R}^d \rightarrow \mathbb{R}$ that's why use the gradiand instead of the derivative

Learning rate can depend on time and we approach the region of the function f where the region is 0. We keep on moving in the X axes in the direction where the function is decreasing.

1.1.1 Projected OGD

2 parameters: $\eta > 0$ and $U > 0$

Initialisation: $w_1 = (0, \dots, 0)$

For $t = 1, 2, \dots$

1) **Gradient step:**

$$w'_{t+1} = w_t - \frac{\eta}{\sqrt{t}} \nabla \ell_t(w_t) \quad (x_t, y_t) \rightsquigarrow \ell_t$$

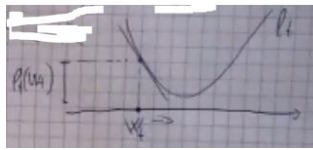


Figure 1.1:

2) **Projection step:**

$$w_{t+1} = \arg \min_{w: \|w\| \leq U} \|w - w'_{t+1}\|$$

Projection of w'_{t+1} onto the ball of radius U .

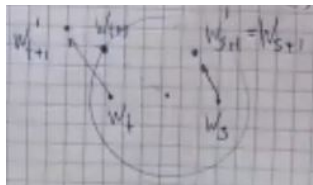


Figure 1.2:

Now we define the Regret:

$$U_T^* = \arg \min_{U \in \mathbb{R}^d, \|U\| \leq U} \frac{1}{T} \sum_{t=1}^T \ell_t(U)$$

We are interested in bounding the regret $R_T(U_T^*)$

I will fix ℓ_1, \dots, ℓ_t let $U = U_T^*$ for U .

Taylor's theorem for multivariate functions

Let's look a univariate first $f : \mathbb{R} \rightarrow \mathbb{R}$ (*has to be twice differentiable*)
 $w, u \in \mathbb{R}$

$$f(u) = f(w) + f'(w)(u - w) + \frac{1}{2} f''(\xi)(u - w)^2$$

For the multivariate case:

$f : \mathbb{R}^d \rightarrow \mathbb{R}$ twice differentiable $\forall u, w \in \mathbb{R}^d$

$$f(u) = f(w) + \nabla f(w)^T (u - w) + \frac{1}{2} (u - w)^T \nabla^2 f(\xi) (u - w)$$

where ξ is some point on the segment going u and w . We have the Hessian matrix of f :

$$\nabla^2 f(x)_{ij} = \frac{\partial^2 f(x)}{\partial x_i \partial x_j} |_{x = x_i}$$

If f is convex then, $\nabla^2 f$ is positive and semidefinite.
 $\forall x \in \mathbb{R}^d \quad \forall z \in \mathbb{R}^d \quad z^T \nabla^2 f(x) z \geq 0$



Figure 1.3:

Now we can apply this results to our problem: in particular I rearrange the factors

$$f(w) - f(u) \leq \nabla f(w)^T (w - u)$$

This is Ok for f convex and differentiable.

I know that: $u - w^T \nabla^2 f(\xi) (u - w) \geq 0$ because f is convex.

$$\ell_t(w_t) - \ell_t(u) \leq \nabla \ell_t(w_t)^T (w_t - u) \quad \text{Linear Regret}$$

How do we proceed?

The first step of the algorithm is : $w'_{t+1} = w_t - \eta_t \nabla \ell_t(w_t) \quad \eta_t = \frac{\eta}{\sqrt{t}}$

$$= -\frac{1}{\eta_t} (w'_{t+1} - w_t)^T (w_t - u) = \frac{1}{\eta_t} \left(\frac{1}{2} \|w_t - u\|^2 - \frac{1}{2} \|w'_{t+1} - u\|^2 + \frac{1}{2} \|w_{t+1} - w_t\|^2 \right) \leq$$

$$\leq \frac{1}{\eta_t} \left(\frac{1}{2} \|w_t - u\|^2 - \frac{1}{2} \|w_{t+1} - u\|^2 + \frac{1}{2} \|w'_{t+1} - w_t\|^2 \right)$$

w' disappear and add minus sign. I am saying that $\|w_{t+1} - u\| \leq \|w'_{t+1} - u\|$

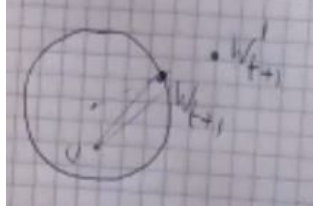


Figure 1.4:

So is telling us that w_{t+1} is closer to u than w'_{t+1}
This holds since the ball is convex.

Now we go back adding and subtracting $\pm \frac{1}{2\eta_{t+1}} \|w_{t+1} - u\|^2$

$$= \frac{1}{2\eta_t} \|w_t - u\|^2 - \frac{1}{2\eta_{t+1}} \|w_{t+1} - u\|^2 - \frac{1}{2\eta_t} \|w_{t+1} - u\|^2 + \frac{1}{2\eta_{t+1}} \|w_{t+1} - u\|^2 + \frac{1}{2\eta_t} \|w_{t+1} - w_t\|^2$$

We group the 1,2 and 3,4 elements and sum them up.

$$R_T(U) = \sum_{t=1}^T (\ell_t(w_t) - \ell_t(u)) \leq$$

This is a **telescopic sum**: $a_1 - a_2 + a_2 - a_3 + a_3 - a_4 + \dots + a_t - a_{t+1} + 1$ and everything in the middle cancel out and remains first and last terms.

$$\leq \frac{1}{2\eta_t} \|w_1 - u\|^2 - \frac{1}{\eta_{T+1}} \|w_{T+1} - u\|^2 + \frac{1}{2} \sum_{t=1}^T \|w_{t+1} - u\|^2 \left(\frac{1}{\eta_{t+1}} - \frac{1}{\eta_t} \right) + \frac{1}{2} \sum_{t=1}^T \frac{\|w'_{t+1} - w_t\|^2}{\eta_t}$$

where $w_1 = 0$ and $\|w_{t+1} - u\|^2 \leq 4U^2$ and $\|w'_{t+1} - w_t\|^2 = \eta_t^2 \|\nabla \ell_t(w_t)\|^2$
We know that $\eta_t = \frac{\eta}{\sqrt{t}}$ so $\eta_1 = \frac{\eta}{\sqrt{1}} = \eta$

$$R_T(U) \leq \frac{1}{2\eta} U^2 - \frac{1}{2\eta_{T+1}} \|w_{T+1} - U\|^2 + 2U^2 \sum_{t=1}^{T-1} \left(\frac{1}{\eta_t} - \frac{1}{\eta_{t+1}} \right) + \frac{\|w_{T+1} - U\|^2}{2\eta_{T+1}} - \frac{\|w_T - U\|^2}{\eta_T} + \frac{1}{2} \sum_{t=1}^T \eta_t \|\nabla \ell_t(w_t)\|^2$$

where **red values** cancel out.

I assume that square loss is bounded by some number G^2 : $\|\nabla \ell_t(w_t)\|^2 \leq G^2$

Also, it's a telescopic sum again and all middle terms cancel out.

$$\max_t \|\nabla_t(w_t)\|^2 \leq G$$

$$R_T(U) \leq \frac{1}{2\eta} U^2 + 2U^2 \left(\frac{1}{\eta_T} - \frac{1}{\eta_1} \right) + \frac{G^2}{2} \eta \sum_{t=1}^T \frac{1}{\sqrt{t}} \quad \eta_t = \frac{1}{\sqrt{t}}$$

where **red values** cancel out.

Now how much is this sum $\sum_{t=1}^T \frac{1}{\sqrt{t}}$?

It is bounded by the integral $\leq \int_1^T \frac{dx}{\sqrt{x}} \leq 2\sqrt{T}$

$$R_T(U) \leq \frac{2U^2\sqrt{T}}{\eta} + \eta G^2\sqrt{T} = \left(\frac{2U^2}{\eta} + \eta G^2 \right) \sqrt{T}$$

$$\eta = \frac{U}{G\sqrt{2}}$$

So finally:

$$\frac{1}{T} \sum_{t=1}^T \ell_t(w_t) \leq \min_{\|u\| \leq U} \frac{1}{T} \sum_{t=1}^T \ell_t(u) + U G \sqrt{\frac{8}{T}}$$

$$R_T(U) = \frac{1}{T} \sum_{t=1}^T (\ell_t(w_t) - \ell_t(u)) \quad \forall u : \|u\| \leq U : R_T(U) = O\left(\frac{1}{\sqrt{T}}\right)$$

Basically my regret is gonna go to 0.

For *ERMinH* where $|H| < \infty$, variance error vanishes at rate $\frac{1}{\sqrt{m}}$

The bound $U G^2 \sqrt{\frac{8}{T}}$ on regret holds for any sequence ℓ_1, ℓ_2, \dots of convex and affordable losses, If $\ell_t(w) = \ell(w^T x_t, y_t)$ then the bound holds for any sequence of data points $(x_1, y_1), (x_2, y_2) \dots$.

This is not a statistical assumption but mathematical so stronger.