Graph - Lezione 1 - 28/10/2019 sabato 2 novembre 2019 12:02

Introduction

Some Element of theory and combinatory

Discrete time Markov chain --> discrete in time and space and useful to model movements on a graph.

Markov chain to analyse random graph to represent for example social networks.

Probability space Probability space

Let Ω be any set and let Σ be some "appropriate" class of subsets of Ω.

Elements of Σ are called events.

For $A \subseteq \Omega$ we write A^C for the complement of A in Ω , i.e.

 $A^{C} = \{s \in \Omega : s \notin A\}.$

The randomness of the experiment is summerize by Omega. Omega is defined a family of class of appropriate subset of Omega. Many cases sigma is all subset of Omega. In general is important that the family (sigma) not only includes the event but also the complements of the event AC.

Definition A probability measure on Ω is a function $P:\Sigma \to [0,1],$ satisfying

- $P(\emptyset) = 0.$
- $P(A^C) = 1 P(A)$ for any event A.
- If A and B are disjoint events (that is if $A \cap B = \emptyset$), then $P(A \cup B) = P(A) + P(B)$. More generally, if A_1, A_2, \ldots is a countable sequence of disjoint events $(A_i \cap A_j = \emptyset$, for any
- $i \neq j$), then $P(\bigcup_{t=1}^{\infty} A_t) = \sum_{t=1}^{\infty} P(A_t)$.

Note that the first two conditions imply that $P(\Omega) = 1$.

The triple (Ω, Σ, P) is called probability space.

Is a function from the probability function from 0 to 1. Probability of empty set should be zero --> nothing is happening. P(complement of event) = 1 - P (event). If A and B are disjoint event the probe of the union is the sum of the prob of the single event. The sum should be good even for infinity disjoint events.

Conditional Probability Conditional probability

Definition If A and B are events, and P(B) > 0, we define the conditional probability of A given B as $P(A|B) = \frac{P(A \cap B)}{P(B)}$ Interpretation: P(A|B) is how likely we consider that A happens, knowing that B happened

How likely we expect realization of A knowing B.

Example

A= Tomorrow here will rain B= Today a storm occurred 100 Km on the west of my position

If I don't know anything about weather forecast or conditions in the surrounding (and I don't know if *B* occurred) I can only guess that $P(A) = P(\text{tomorrow here will rain}) = \frac{1}{2}$.

But if I know that B happened, it becomes more likely that tomorrow here will rain, thus $P(A|B) > \frac{1}{2}$.

Independence

Definition Two events A and B are said to be independent if $P(A \cap B) = P(A)P(B).$

More in general Definition

The events A_1, \ldots, A_k are said to be **independent** if for any $l \le k$ and any $i_1, \ldots, i_l \in \{1, \ldots, k\}$ with $i_1 < i_2 < \cdots < i_l$ we have

 $P(A_{i_1} \cap A_{i_2} \cap \cdots \cap A_{i_l}) = P(A_{i_1}) \cdot P(A_{i_2}) \cdot \cdots \cdot P(A_{i_l}).$

The probability of the intersecion of the two events is the product of the probability.

Why is related to the conditional probability? Since we know the prob of A | B so P(A | B) = P(A)

Note that if A and B are independent, then, since $P(A|B) = \frac{P(A \cap B)}{P(B)}$, we have

 $P(A \cap B) = P(A|B)P(B) = P(A)P(B)$

Then

P(A|B) = P(A)

Example. A = Tomorrow here will rain B = Today I make a cake

 \boldsymbol{A} is not influenced by \boldsymbol{B} and viceversa, thus they are independent and P(A|B) = P(A).

If A and B are independent the probability of intersection is the probability of the two intersection. If A and B are

In practice, in particular if the space $\boldsymbol{\Omega}$ is finite, we compute the probability of an event A as

$P(A) = \frac{\# \text{ cases in favor of } A}{\mu}$

possible cases The correct counting of cases is the subject of combinatorics.

Combinatorics: counting problems

[C.M.Grinstead, J.L.Snell, Introduction to Probability, AMS publisher, 1997 - Chapter 3]

Consider an experiment that takes place in several stages and is such that the number of outcomes m at the nth stage is independent of the outcomes of the previous stages. The number m may be different for different stages.

We want to count the number of ways that the entire experiment can be carried out.

An experiment in several stages. The outcomes of m is indepedent of the outcomes of the previos stage. We wanto to count the number of way the number of experiments can be go on.

 $\label{eq:Example 1. You are eating at Emile's restaurant and the waiter$ informs you that you have

(a) two choices for appetizers: soup or juice;

(b) three for the main course: a meat, fish, or vegetable dish;

(c) two for dessert: ice cream or cake.

How many possible choices do you have for your complete meal? We can represent this concept with a three.





Your menu is decided in three stage. At each stage the number of possible choices does not depend on what is chosen in the previous stages: two choices at the first stage, three at the second, and two at the third.

From the tree diagram we see that the total number of choices is

the product of the number of choices at each stage.

In this example we have $2 \cdot 3 \cdot 2 = 12$ possible menus. At each stage you have different number of possible choises. So, number m is different from different stages. Counting the number of leaves you have all the possible menus that you can compose. If you want to count them you have to multiply 2 appetizer * 3 main course * 2 desert = 12. In general it's a good procedure and we can generalize this rules.

Our menu example is an example of the following general counting technique:

Counting technique. A task is to be carried out in a sequence of r stages. There are n_1 ways to carry out the first stage; for each of these n_1 ways, there are n_2 ways to carry out the second stage; for each of these n_2 ways, there are n_3 ways to carry out the third stage, and so forth. Then the total number of ways in which the entire task can be accomplished is given by the product

$N = n_1 \cdot n_2 \cdot \cdots \cdot n_r$

If the stage are indepedent the total number is given by the product of the number of ways in each step.

Tree diagrams

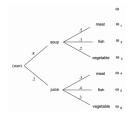
It will often be useful to use a tree diagram when studying probabilities of events relating to experiments that take place in stages and for which we are given the probabilities for the outcomes at each stage.

 $\textbf{Example 1}: \ \textbf{consider only appetizers and main course, and assume}$ that the owner of Emile's restaurant has observed that 80% of his customers choose the soup for an appetizer and 20% choose juice. Of those who choose soup, 50% choose meat, 30% choose fish,

and 20% choose the vegetable dish. Of those who choose juice for an appetizer, 30% choose meat, 40% choose fish, and 30% choose the vegetable dish.

We represent these probabilities on the tree diagram.

Why can be useful to introduce these three diagrams? Using the example you can imaging that the owner of the restaurant want toforget about the dessert. The owner observe that the 30% choses appetizer and the other 30% choses soup. We can represent this example with a three diagram.



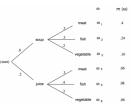
We choose for our sample space the set $\Omega = \{\omega_1, \ldots, \omega_k\}$ of all possible paths along the tree.

$\ensuremath{\textbf{Question:}}$ what is the probability that a customer chooses first

soup and then meat? These means that we have 6 possible compositions of our meal. 6 possible outcomes that we label

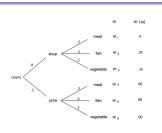
with the symbol w1. ...wk.

We have to moltiply 0.8 * 0.5 to get soup and meat



Answer: $P([1st \ soup]) \cdot P([2nd \ meat|1st \ soup]) = 0.8 \cdot 0.5 = 0.4$

This suggests choosing our probability distribution for each path through the tree to be the product of the probabilities at each of the stages along the path.



Note that $\sum_{i=1}^{6} m(\omega) = 1$. And if we want to know the probability that a customer eas meat, whatever appetizer he/she gets, we sum the probabilities of having meat:

P(meat) = 0.4 + 0.06 = 0.46

So we have conditional probability

SECOND Part

If we wanto only to count our possible outcome we can introduce an intstrument for the counting which is a lot automatical. So first of all, image that we have a finite set A with a finite number of elements an we want to compute the different reordering of the elements of A. Which mean that for example our set of three elements, we want to count the element reorder in different sequences. We are counting the permutations of the elements of A. If A scompose by 3 elements the possible permutation are 6.

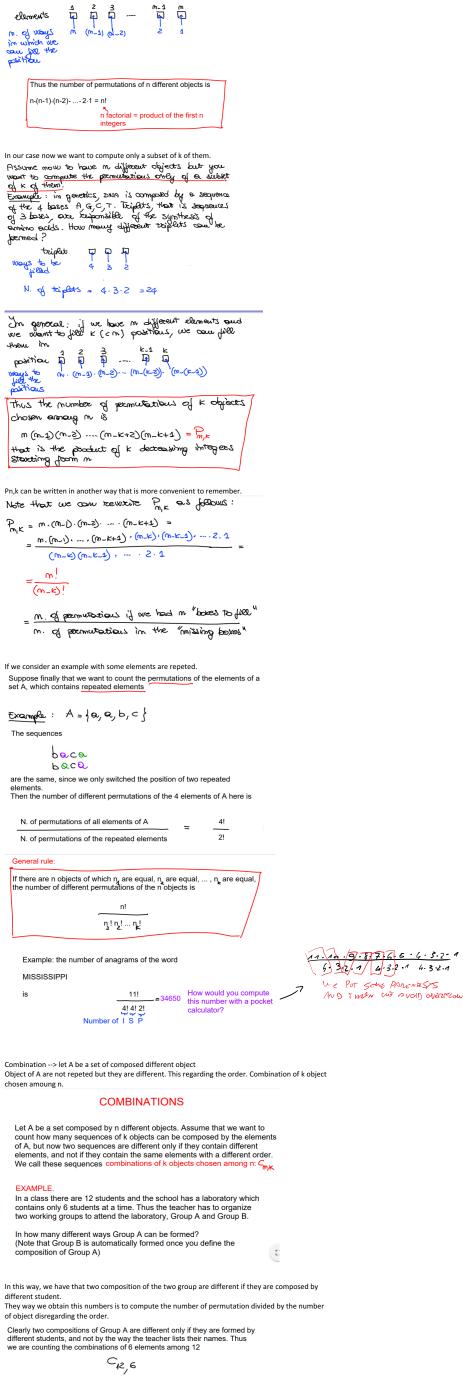
PERMUTATIONS

DEFINITION. Let A be a finite set, composed by n distinct elements. Suppose to order the elements of A. A permutation is a reordering of the elements of A.

Example: A=de, b, c} permutations: abc } acb } bca { 6 permitations are possible bac cob cbo

If you want to compute a set of n element we can count n! permutation. Positioning an element we have to subtract it, infact we got then n-1, n-2 ecc till 1.

In general, if A is composed by n objects, how many permutations can we form with its elements?



In order to obtain this number we can compute the number of permutations of 6 objects chosen among 12, and then divide by the number of sequences of 6 objects which differ only for the order of their elements, that is 6!

$$C_{12,6} = \frac{P_{12,6}}{6!} = \frac{12!}{(12-6)!6!} = 924$$

So we can get a general rule.

General rule:
The number of combinations of k objects chosen among n is given by
$C_{m_{j}\kappa} \approx \frac{P_{m_{j}\kappa}}{\kappa_{j}} = \frac{n!}{(n-k)! k!} \approx {n \choose k}$ Binomial coefficient
What is an efficient way to compute $C_{\rm fryK}$ with a pocket calculator or a computer?

The same strategy that we already introduce. Compute the ratio 2 by 2.

Esercizi

UT N WITH & WHITE BALLS AND 3 BLACK GULS WITH DOWN WITH REPLACEMENT Z BALLS 1) PROB THAT Z BALLS HAVE THE SAME COOL 2) POB AT LEAST 1 OF TWO BALL IS BLACK

P(Z SAME COLOUR) WE MUS TO COUNT EVENTS - L. 7

$$a_{1}(x_{1}, x_{2}, x_{2}, x_{2}, x_{2}, x_{3}, x_{4})$$

$$a_{2}(x_{2}, x_{2}, x_{2}, x_{3}, x_{4}, x_{4},$$

53,10